

Harmonised European Solutions for Testing Automated Road
Transport

HEADSTART's Methodology in a nutshell



# Agenda

- ✓ Introduction
- ✓ Motivation
- ✓ HEADSTART's Overall Methodology



## **Event rules and process**

- ✓ Webinar is being recorded
- ✓ Slides and recording will be shared and published on <u>HEADSTART website</u>
- ✓ Questions can be raised via <u>www.slido.com</u> with event code: #HEADSTART

  The questions are gathered and where possible raised by the webinar moderator at fixed time slots during the webinar to the presenters.
- ✓ Do not wait until the end of the presentation! If you have questions, just send them to us!



✓ Please, avoid using the GoToMeeting chat as your question may not arrive to us.



### Introduction

- ✓ Goal of this Meeting?
- → Get external expert feedback on the HEADSTART Methodology
- ✓ Feedback will be integrated by refinement of the methodology

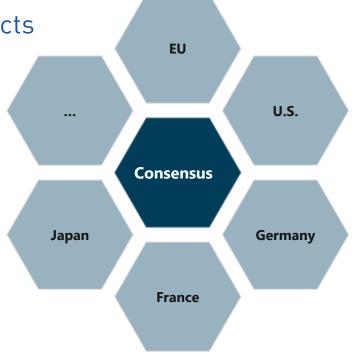


Where does the HEADSTART Methodology come from?



Where does the HEADSTART Methodology come from?

- ✓ State of the art analysis of international and national projects
- ✓ Harmonization of present and past projects
- ✓ Utilizing common databases to analyse data
- ✓ Testing of selected relevant scenarios





Why do we need a scenario-based safety assurance?



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#### Safety assurance by test drives?

- Sample calculations ranging up to billions of kilometers
- → Not feasible

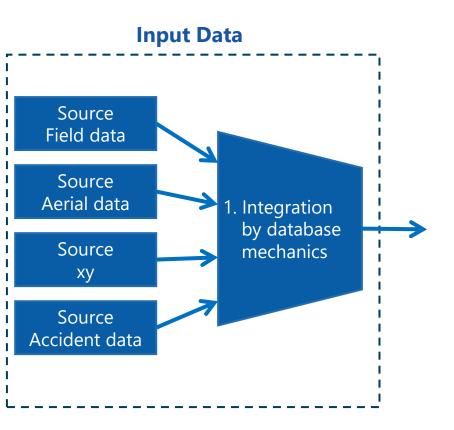
#### Safety assurance by expert knowledge?

- No evaluation methodology available for automated driving (L3+)
- → Not available

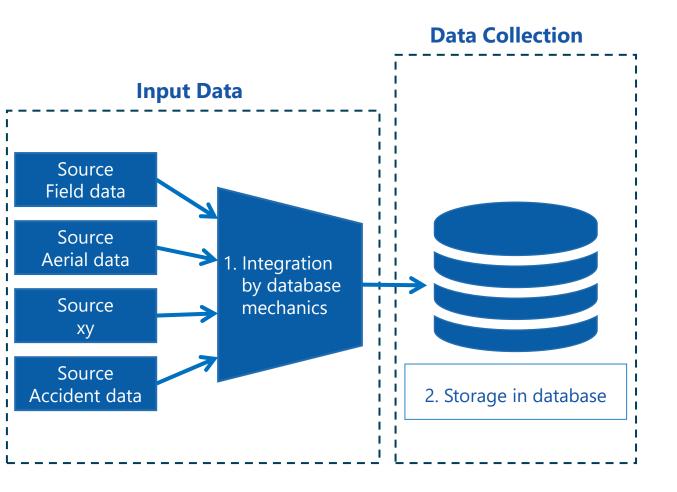


How can such a methodology look like?

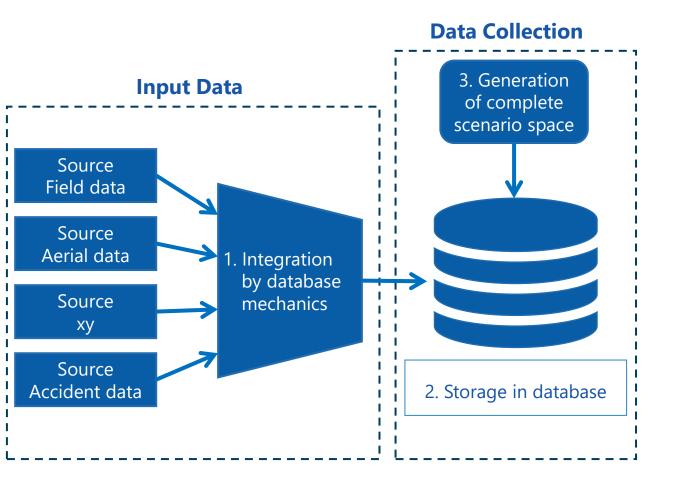




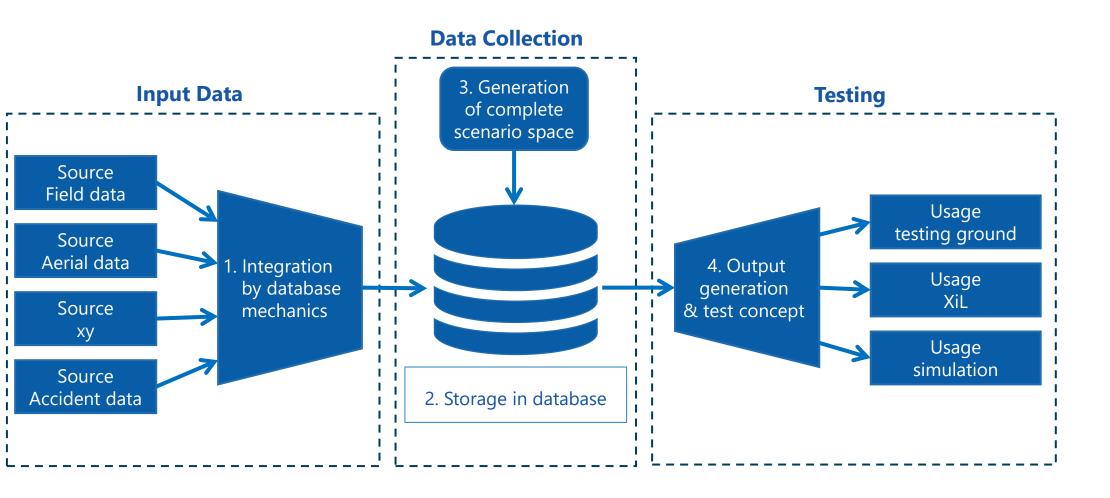




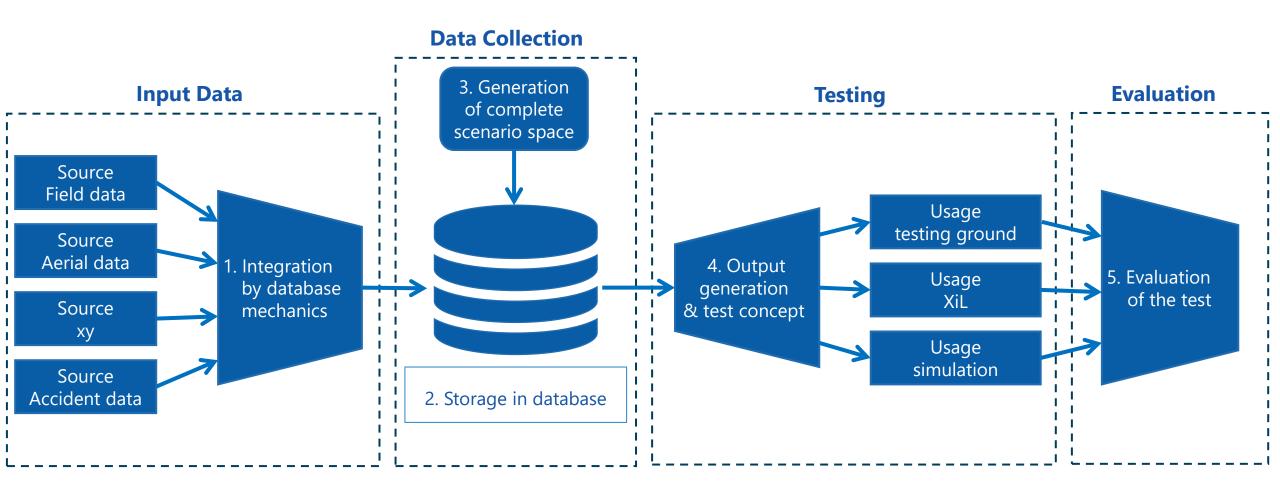




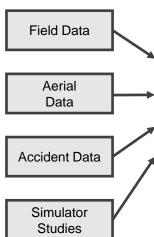


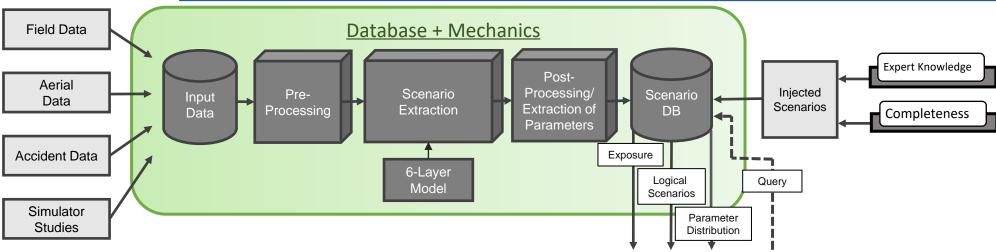


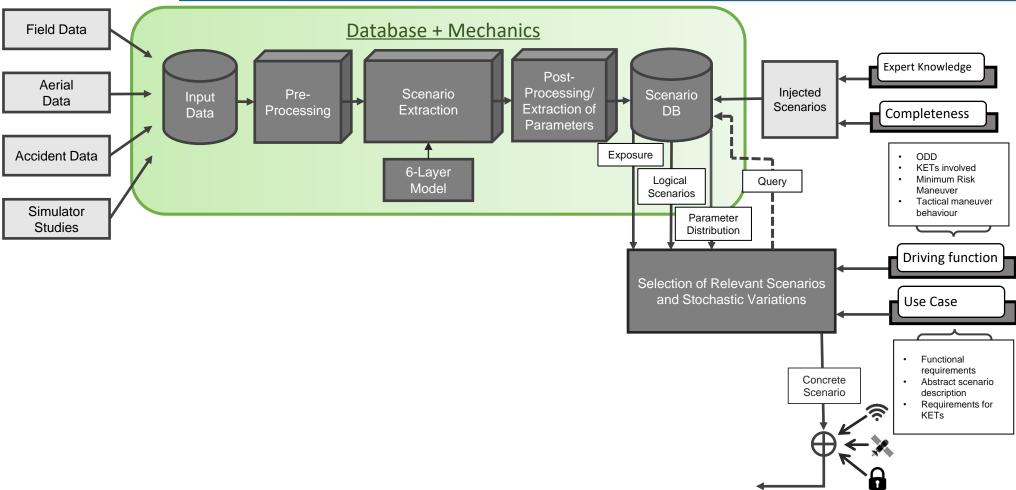


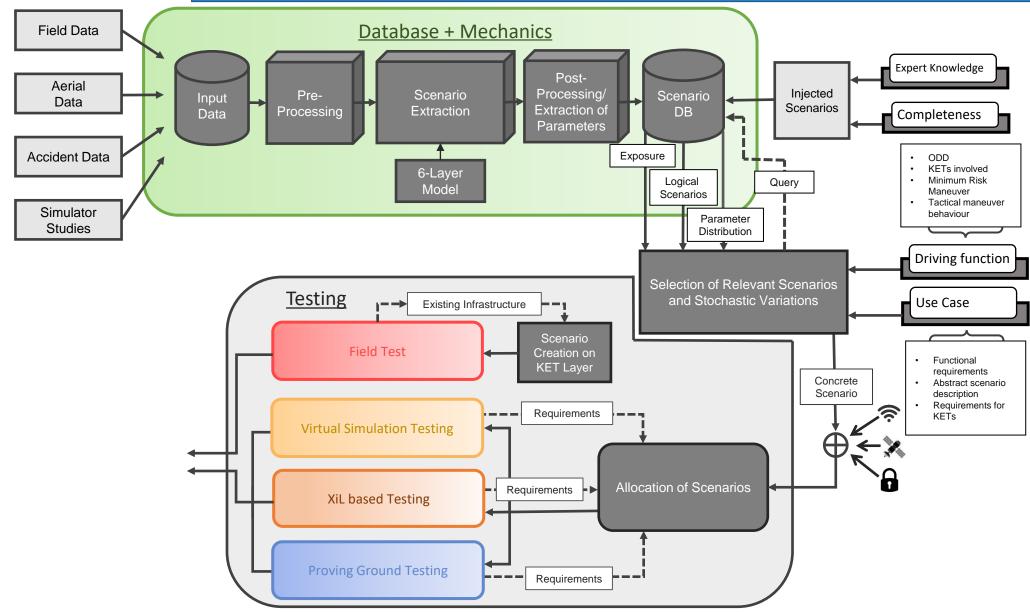


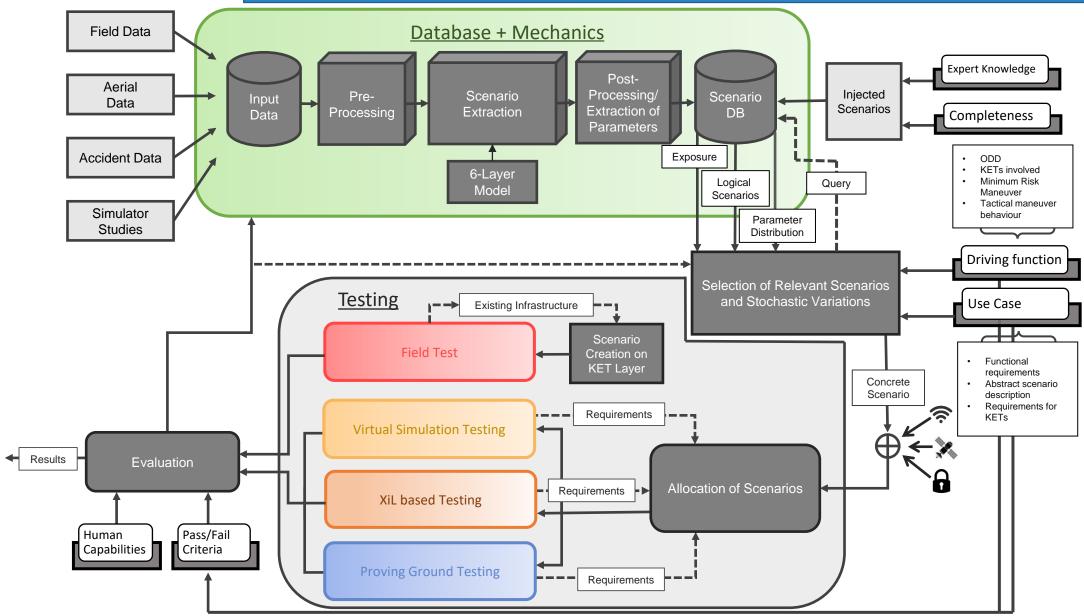


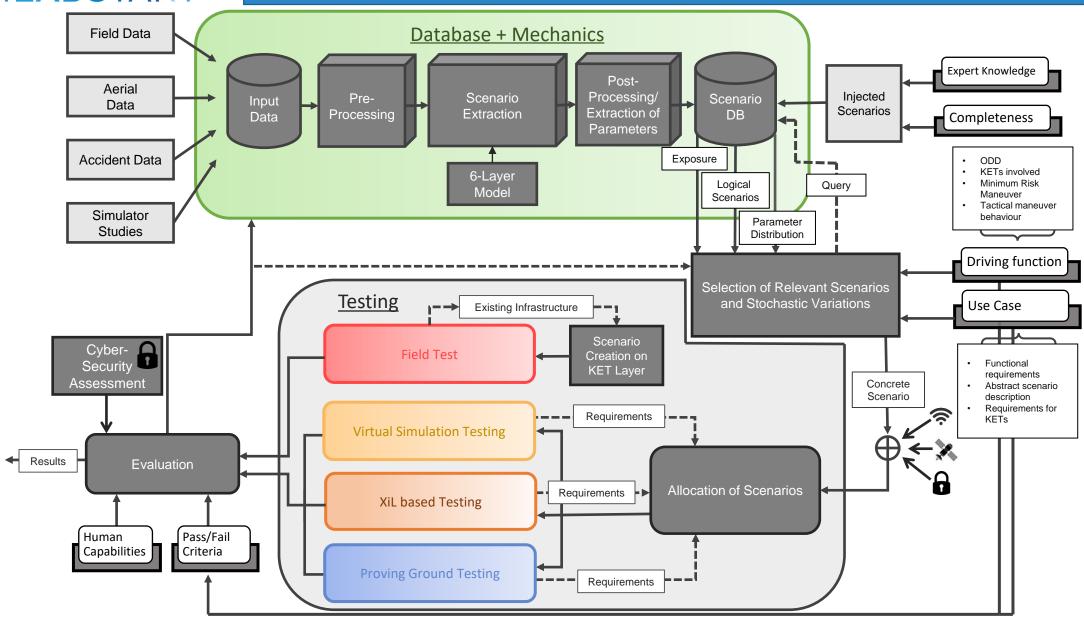






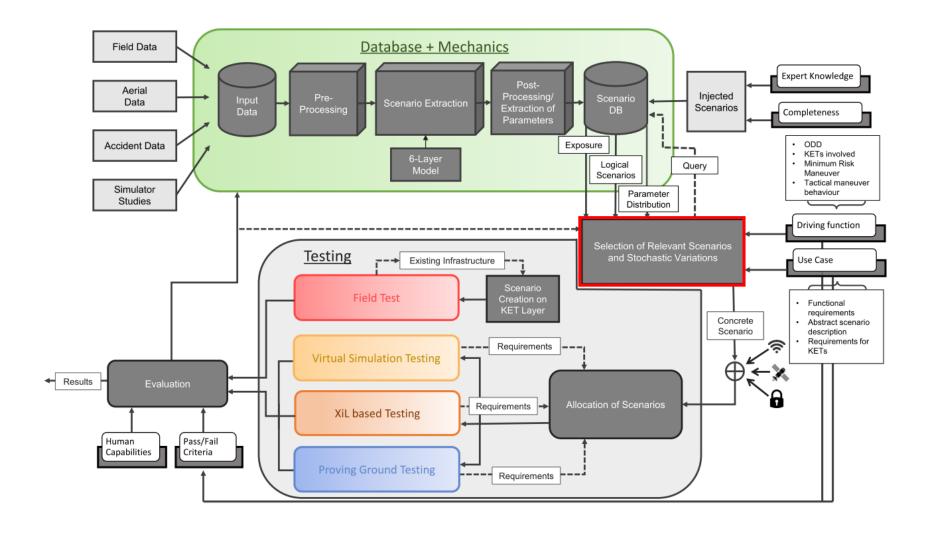








## **Scenario Selection**





# Layer Model

Layer 6

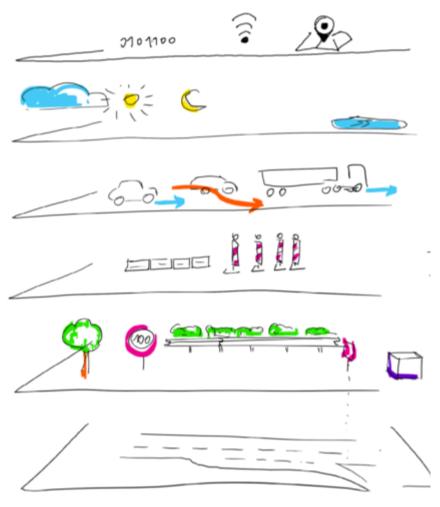
Layer 5

Layer 4

Layer 3

Layer 2

Layer 1



#### **Digital information**

e.g. V2X information on traffic signals, digital map data

#### **Environmental conditions**

e.g. Light situation, weather (rain, snow, fog)

#### **Moving Objects**

e.g. Vehicles, pedestrians, other moving objects

#### **Temporal modifications and events**

e.g. Road construction, traffic cones, fallen trees

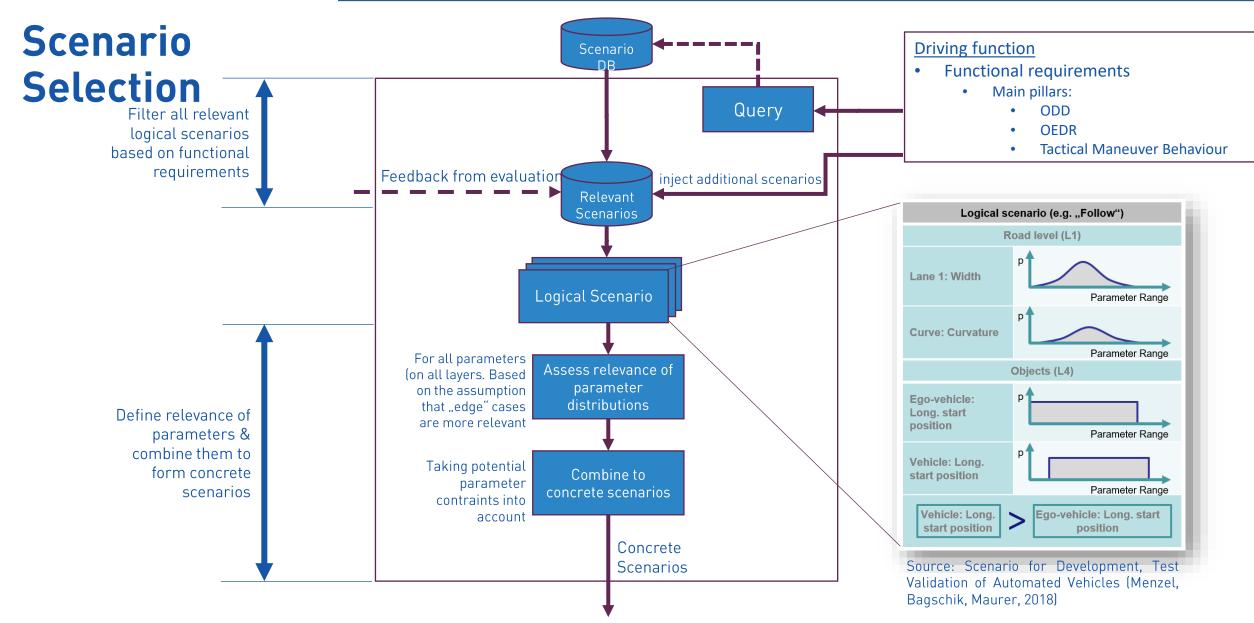
#### **Road furniture and Rules**

e.g. Traffic signs, railguards, lane rules, bot dots

#### **Road layer**

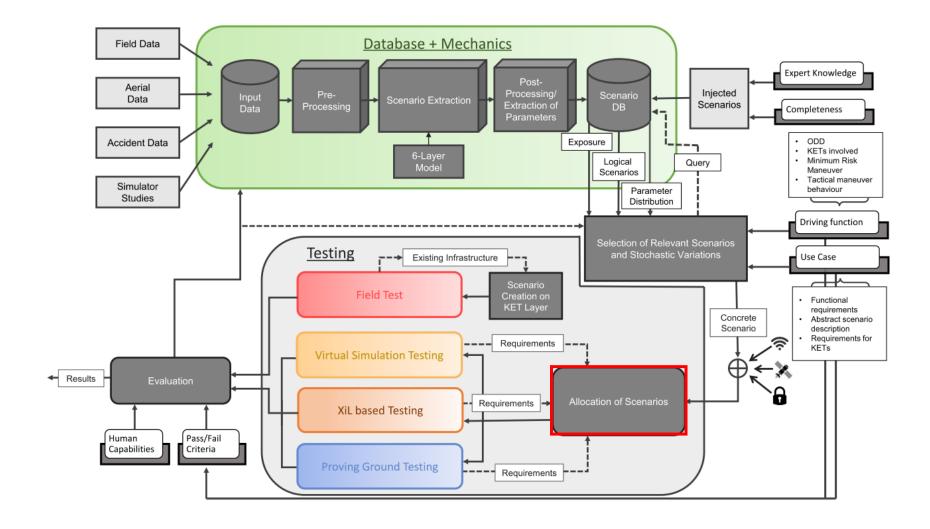
e.g. Road geometry, road unevenness, lane logic







## **Scenario Allocation**

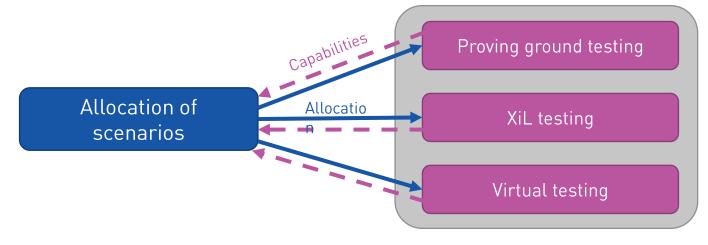




### Scenario Allocation

- ✓ Each test instance has its advantages and restrictions
- ✓ Safety, testing cost, testing time and other parameters must be taken into account in the allocation process

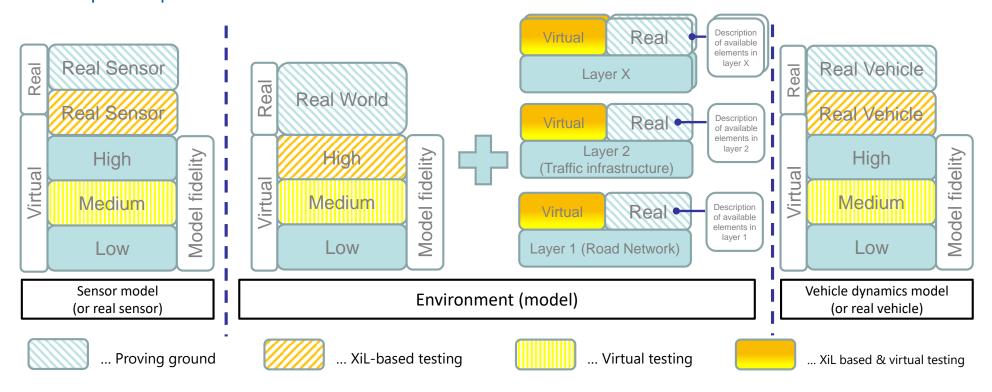
✓ Objective → Define how to allocate the selected concrete scenarios to each test method to find the "best fit"





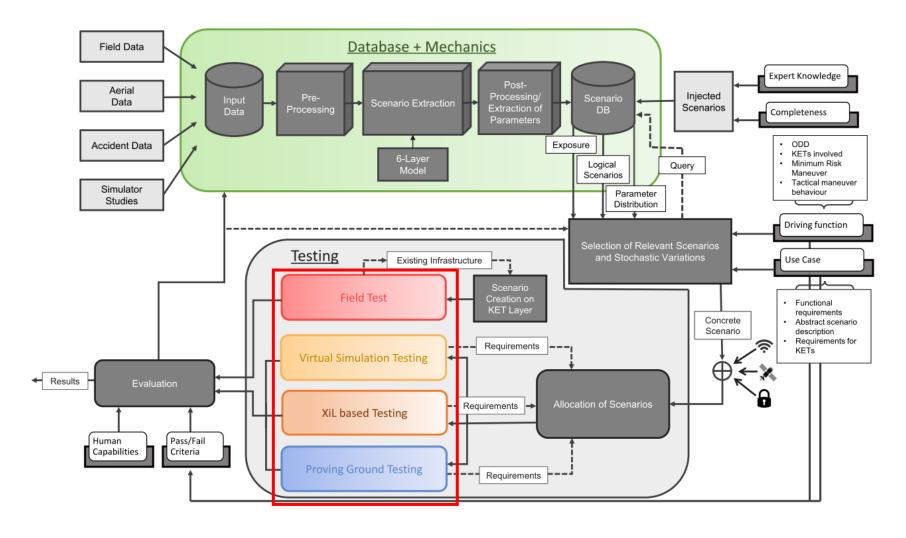
## **Scenario Allocation**

- ✓ Definition of the capabilities for "Sensor", "Environment" and "Vehicle Dynamics"
- ✓ Use of the map of capabilities:





### **Test Execution**





## **Scenario Execution**

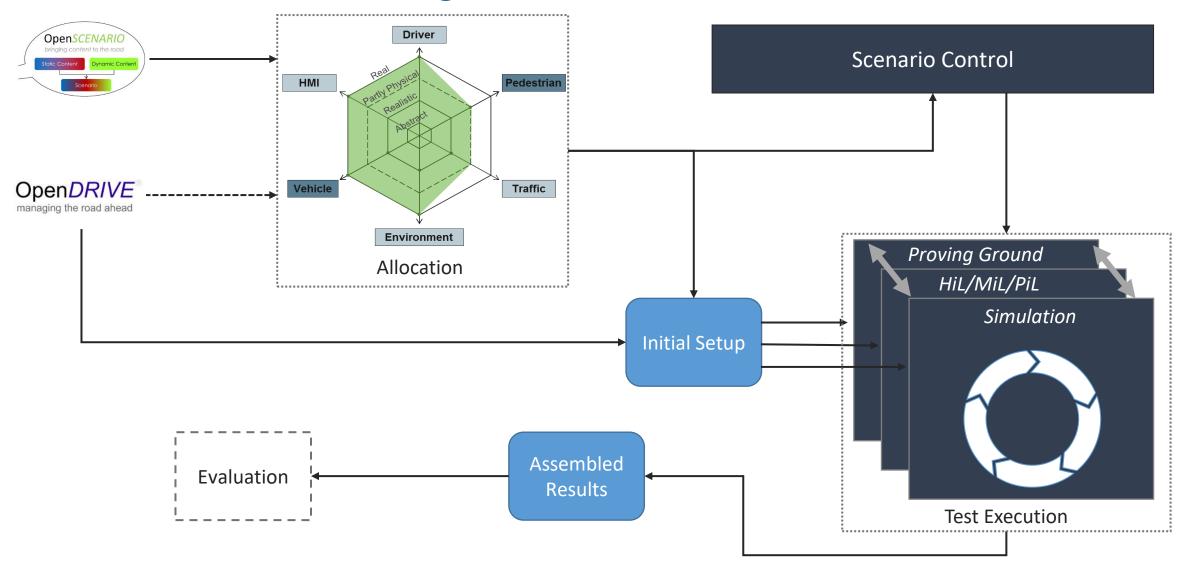
- ✓ Testing Facilities
  - Proving Grounds
  - Simulation
  - XiL Based
  - Field Operational Tests

- ✓ Unified Interfaces
  - Open Simulation Interface (OSI)
  - Functional Mock-up Interface (FMI)

- ✓ Open Standards
  - OpenSCENARIO
  - OpenDRIVE
  - OpenCRG



## **XiL-Based Testing**





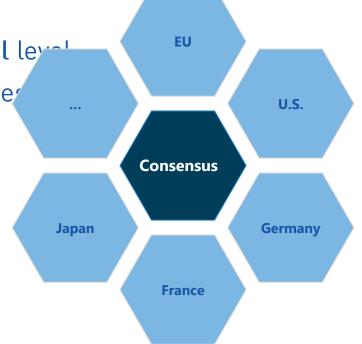
## Summary

- ✓ The HEADSTART Methodology is a living process
  - Need for expert input to refine the methodology

✓ High effort for safety assurance on national and international lexal

✓ HEADSTART tries to harmonize different projects and initiative:

→ International **cooperation** is key to safety assurance





## Thank you!

Any questions?

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